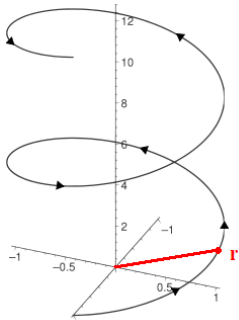


Parametric Surfaces

In unit 9, we saw it is often easiest to define a curve in space with parametric equations, such as:

$$\mathbf{r}(t) = \cos(t) \cdot \hat{\mathbf{i}} + \sin(t) \cdot \hat{\mathbf{j}} + t \cdot \hat{\mathbf{k}} \quad \text{representing all the points of a helix spiraling along the } z\text{-axis}$$

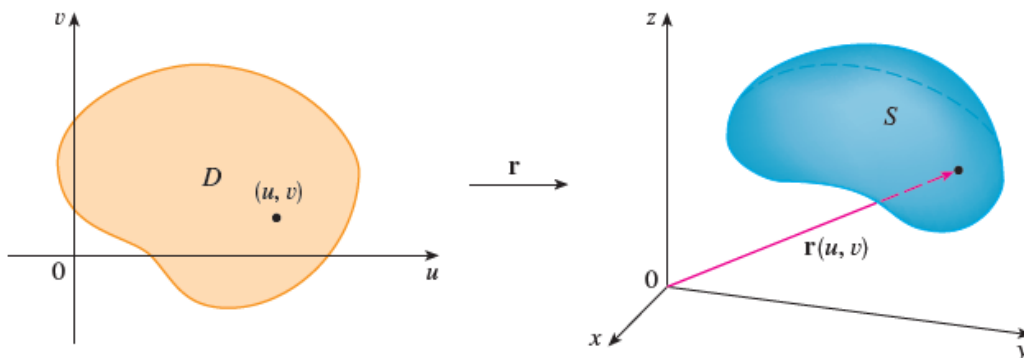
What the equation above indicates is that where you are in space (the \mathbf{r} position vector) depends upon some functions, namely $\cos(t)$, $\sin(t)$ and t , which in turn depends upon some value, t . We can get away with using only one parameter, t , because the helix is a one-dimensional curve.



But how can we represent a two-dimensional surface parametrically? It would make sense that if a one-dimensional curve requires one parameter, a two-dimensional surface would need two (conventionally u and v) used in the position function such that:

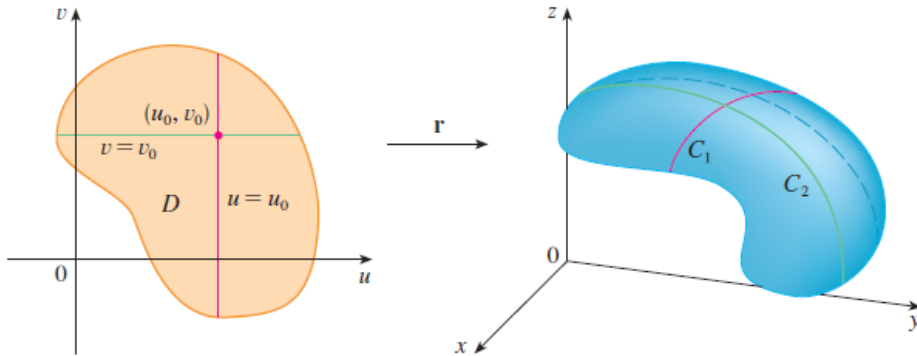
$$\mathbf{r}(u,v) = f(u,v) \cdot \hat{\mathbf{i}} + g(u,v) \cdot \hat{\mathbf{j}} + h(u,v) \cdot \hat{\mathbf{k}}$$

What the equation above means is that we can define a series of points in space (the function \mathbf{r}) that depend upon the f , g , and h functions and the values of those functions depend upon where you are in the uv plane (shown below). The tricky part is realizing that the uv plane is not some spatial entity like the xy -plane; it's a kind of abstract function space.



You can imagine walking around the uv plane and every time you stand at a given uv -coordinate, you look down and see three coordinates (x , y , and z) for actual 3D space. Imagine putting a tiny hovering drone at those coordinates, then moving to a slightly different spot on the uv plane, reading the x , y , and z values below you, placing another drone there, etc. Once you have walked over the entire uv plane and done this, the drone fleet will map-out the curve, S .

Imagine clearing the skies and now, instead, walking entirely along the v direction of this abstract uv plane. You would place a series of drones that would only form a curve along the full surface, S . This is called a *grid curve*. Likewise, you could walk along the u direction of the uv plane and map-out a different grid curve.



Example: A cone is a surface which follows the equation: $z = \sqrt{x^2 + y^2}$ for $0 \leq z \leq 5$. Write this same surface with a parametric equation.

The straightforward answer would be:

$$\mathbf{r}(x,y) = x \cdot \hat{\mathbf{i}} + y \cdot \hat{\mathbf{j}} + \sqrt{x^2 + y^2} \cdot \hat{\mathbf{k}}$$

Another possibility is:

$$\text{If we let } z = u, \text{ then } u^2 = x^2 + y^2 = u^2 \cdot \cos^2\theta + u^2 \cdot \sin^2\theta$$

$$\text{allowing } x = u \cdot \cos\theta \quad \text{and} \quad y = u \cdot \sin\theta$$

$$\text{Resulting in } \mathbf{r}(u,\theta) = u \cdot \cos\theta \cdot \hat{\mathbf{i}} + u \cdot \sin\theta \cdot \hat{\mathbf{j}} + u \cdot \hat{\mathbf{k}} \quad \text{with the two parameters } u \text{ and } \theta$$

Here, an obvious grid curve would be one where u is held constant and θ varies from 0 to 2π , creating the circle at some altitude, u .

Example: Write the parametric equation for a sphere with a radius of 5.

We know that $x^2 + y^2 + z^2 = 5$. As seen in unit 19, to convert from Cartesian to spherical coordinates, we imagine a point on the sphere at an angle ϕ above the xy -plane casting a shadow on the xy -plane with length $5 \cdot \cos\phi$. Rotating this shadow from 0 to 2π in the xy -plane gives us:

$$x = 5 \cdot \cos\theta \cdot \cos\phi \quad y = 5 \cdot \sin\theta \cdot \cos\phi \quad z = 5 \cdot \sin\phi$$

$$\mathbf{r}(\phi, \theta) = 5 \cdot \cos\theta \cdot \cos\phi \cdot \hat{\mathbf{i}} + 5 \cdot \sin\theta \cdot \cos\phi \cdot \hat{\mathbf{j}} + 5 \cdot \sin\phi \cdot \hat{\mathbf{k}}$$

Likewise, converting from Cartesian to cylindrical coordinates gives us a way of writing surfaces of revolution with parametric equations. For instance, take the simple function,

$$y = 5 \quad \text{for } 0 \leq x \leq 10.$$

Rotating this around the yz-plane gives us, from 0 to 2π

$$y = 5 \cdot \cos\theta \quad \text{and} \quad z = 5 \cdot \sin\theta \quad \text{and} \quad x = x$$

So the parametric equation would be

$$\mathbf{r}(x, \theta) = x \cdot \hat{\mathbf{i}} + 5 \cdot \cos\theta \cdot \hat{\mathbf{j}} + 5 \sin\theta \cdot \hat{\mathbf{k}}$$

Which works just as well for something like $y = 5\sqrt{x}$:

$$\mathbf{r}(x, \theta) = x \cdot \hat{\mathbf{i}} + 5\sqrt{x} \cdot \cos\theta \cdot \hat{\mathbf{j}} + 5\sqrt{x} \cdot \sin\theta \cdot \hat{\mathbf{k}}$$

Recall that walking through the uv-plane at a constant value of u and a changing v maps out a grid curve in space along the surface, S . We can call this \mathbf{r} as a function of v, so that, at some point on the surface, (u_0, v_0) :

$$\mathbf{r}(u_0, v_0) = x \cdot \hat{\mathbf{i}} + y \cdot \hat{\mathbf{j}} + z \cdot \hat{\mathbf{k}} \quad \text{and}$$

$$\mathbf{r}_v = \frac{d\mathbf{r}}{dv} = \frac{\partial x}{\partial v} \cdot \hat{\mathbf{i}} + \frac{\partial y}{\partial v} \cdot \hat{\mathbf{j}} + \frac{\partial z}{\partial v} \cdot \hat{\mathbf{k}}$$

which represents the slope of the line tangent to the curve at (u_0, v_0) along the v direction

Likewise,

$$\mathbf{r}_u = \frac{d\mathbf{r}}{du} = \frac{\partial x}{\partial u} \cdot \hat{\mathbf{i}} + \frac{\partial y}{\partial u} \cdot \hat{\mathbf{j}} + \frac{\partial z}{\partial u} \cdot \hat{\mathbf{k}}$$

\mathbf{r}_v and \mathbf{r}_u then form a plane which can be defined by the vector normal to that plane, $\mathbf{r}_v \times \mathbf{r}_u$.

Example: For the parametric equations

$$x = u + v \qquad y = 3u^2 \qquad z = u - v$$

Find an equation of the tangent plane at the point (2, 3, 0).

First, solve the equations $2 = u + v$ $3 = 3u^2$ and $0 = u - v$

to find $u = 1$ and $v = 1$

We have $\mathbf{r} = (u + v) \cdot \hat{\mathbf{i}} + (3u^2) \cdot \hat{\mathbf{j}} + (u - v) \cdot \hat{\mathbf{k}}$

$$\mathbf{r}_v = \frac{d\mathbf{r}}{dv} = \frac{\partial x}{\partial v} \hat{\mathbf{i}} + \frac{\partial y}{\partial v} \hat{\mathbf{j}} + \frac{\partial z}{\partial v} \hat{\mathbf{k}} = 1 \cdot \hat{\mathbf{i}} + 0 \cdot \hat{\mathbf{j}} - 1 \cdot \hat{\mathbf{k}}$$

$$\mathbf{r}_u = \frac{d\mathbf{r}}{du} = 1 \cdot \hat{\mathbf{i}} + 6u \cdot \hat{\mathbf{j}} + 1 \cdot \hat{\mathbf{k}} = 1 \cdot \hat{\mathbf{i}} + 6 \cdot \hat{\mathbf{j}} + 1 \cdot \hat{\mathbf{k}}$$

$$\mathbf{r}_v \times \mathbf{r}_u = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ 1 & 0 & -1 \\ 1 & 6 & 1 \end{vmatrix} = 6\hat{\mathbf{i}} - 2\hat{\mathbf{j}} + 6\hat{\mathbf{k}}$$

Referring to unit 6, we see the way to convert this into the equation of a plane is with:

$$6(x - x_0) - 2(y - y_0) + 6(z - z_0) = 0$$

$$6(x - 2) - 2(y - 3) + 6(z - 0) = 0$$

$$3x - y + 3z - 3 = 0$$

Imagine taking this equation for the tangent plane and shrinking down the area to $\Delta u \cdot \Delta v$. This would give us an approximate area for the corresponding patch on the curve, S . We could then find the sum of these patches over the whole uv -plane to find the surface area of S .

Shrinking $\Delta u \cdot \Delta v$ to $du \cdot dv$ gives us the actual equation for the area of the surface:

$$\text{Area of } S = \iint |\mathbf{r}_u \times \mathbf{r}_v| \cdot du \cdot dv$$

However, a more useful form is in terms of x , y , and z rather than in terms of u and v . Suppose we have some shape above the xy -plane such that $z = f(x,y)$. Given that $x = x$ and $y = y$,

$$\mathbf{r}_x = \frac{df}{dx} = \frac{d}{dx} (x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z(x,y)\hat{\mathbf{k}}) = \hat{\mathbf{i}} + \frac{\partial z}{\partial x} \hat{\mathbf{k}}$$

Likewise, $\mathbf{r}_y = \hat{\mathbf{j}} + \frac{\partial z}{\partial y} \hat{\mathbf{k}}$

The cross product $\mathbf{r}_x \times \mathbf{r}_y = -\frac{\partial z}{\partial x} \hat{\mathbf{i}} - \frac{\partial z}{\partial y} \hat{\mathbf{j}} + 1 \hat{\mathbf{k}}$

The magnitude of a three dimension vector is just $\sqrt{x^2 + y^2 + z^2}$

so the magnitude of this cross product is $\sqrt{1^2 + \left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2}$

and, using the same form as the area equation above:

$$\text{Area of } S = \iint \sqrt{1 + \left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2} \cdot dx \cdot dy$$

Example: Find the area of the plane $3x + 2y + z = 6$ that lies in the first octant.

$$z = 6 - 3x - 2y$$

$$\frac{\partial z}{\partial x} = -3$$

$$\frac{\partial z}{\partial y} = -2$$

$$\text{Area} = \int_0^3 \int_0^{2-\frac{2y}{3}} \sqrt{1 + (-3)^2 + (-2)^2} \cdot dx \cdot dy$$

$$= \int_0^3 \int_0^{2-\frac{2y}{3}} \sqrt{14} \cdot dx \cdot dy$$

$$= 3\sqrt{14}$$